

4 Finger Manipulator Jaw



4-Finger Manipulator Jaw is the first choice for the vast majority of ROV Operators around the world. The 4 fingered manipulator jaw is intended as a hydraulically operated tool for attachment to a Schilling Robotics work-class ROV manipulator arm. The product is ideal for ROV operations where a combination of precision, flexibility and strength are required.

Specifications

Dimensions	Ø 115 x 263 mm
Cylinder Working Pressure	207 Bar
Maximum jaw opening	170 mm (Jaw made before 2012: 165mm)
Materials	7000 msw
Depth rating	S165M Stainless steel