

3 Finger Manipulator Jaw



3-Finger Manipulator Jaw is the first choice for the vast majority of ROV Operators around the world. The 3 fingered manipulator jaw is intended as a hydraulically operated tool for attachment to a Schilling Robotics work-class ROV manipulator arm. The product is ideal for ROV operations where a combination of precision, flexibility and strength are required.

Specifications

Dimensions	Ø 115 x 263 mm
Cylinder Working Pressure	207 Bar
Maximum jaw opening	170 mm (Jaw made before 2016: 165 mm)
Depth rating	7000 msw
Material	S165M Stainless steel
Weight	5.1 kg