

Imenco 4-Finger Manipulator Jaw

Imenco's 4-Finger Manipulator Jaw is the first choice for the vast majority of ROV Operators around the world.

The 4 fingered manipulator jaw is intended as a hydraulically operated tool for attachment to a Schilling Robotics work-class ROV manipulator arm.

The product is ideal for ROV operations where a combination of precision, flexibility and strength are required.



Technical Specification

Main Dimensions:	Ø115 x 263mm
Cylinder Working Pressure:	207 Bar
Maximum jaw opening:	170mm (For jaw made before 2012: 165mm)
Depth rating:	7000msw
Material:	S165M Stainless steel



WARNING!
DO NOT operate the machinery before reading the instruction manual



CUATION!
Operator shall read the Instruction Manual before using



CUATION!
Pinch point – Keep hands clear.



CUATIONS!
Heavy object